

# Stateful Structural Operational Semantics



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# Structural Operational Semantics [Plotkin 1981]

**Idea:** Specify program/process behaviour by inductive transition rules.

$$\frac{p \xrightarrow{a} p'}{p \parallel q \xrightarrow{a} p' \parallel q} \qquad \frac{q \xrightarrow{a} q'}{p \parallel q \xrightarrow{a} p \parallel q'}$$

**Key issue:** **compositionality** – is behavioural equivalence a congruence?

$$p_i \sim q_i \quad (i = 1, \dots, n) \implies f(p_1, \dots, p_n) \sim f(q_1, \dots, q_n) \quad (f \in \Sigma)$$

Typically long and complex proof 😞

**Goal:** Rule formats that guarantee compositionality!

**GSOS rules [Bloom, Istrail & Mayer 1995]:**

$$\frac{\{p_i \xrightarrow{a} q_{ij}\}_{i,j,a} \quad \{p_i \xrightarrow{b}\}_{i,b}}{f(p_1, \dots, p_n) \xrightarrow{c} t(\dots, p_i, \dots, q_{ij}^a, \dots)} \quad (f \in \Sigma)$$

... guarantee compositionality with respect to bisimilarity.

**Categorically [Turi & Plotkin 1997]:** Natural Transformations

$$\underbrace{\Sigma(X \times (\mathcal{P}_f X)^L)}_{\text{premisses}} \longrightarrow \underbrace{(\mathcal{P}_f \Sigma^* X)^L}_{\text{conclusion}} \quad (X \in \text{Set})$$

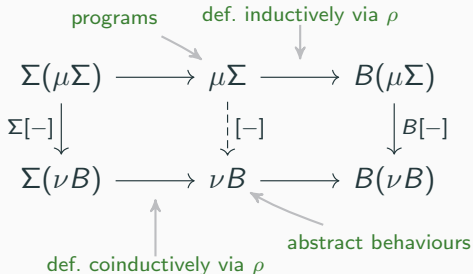
**Abstract GSOS law** of  $\Sigma: \mathcal{C} \rightarrow \mathcal{C}$  over  $B: \mathcal{C} \rightarrow \mathcal{C}$

$$\Sigma(X \times BX) \longrightarrow B\Sigma^* X \quad (X \in \mathcal{C})$$

# Abstract GSOS [Turi & Plotkin 1997]

$$\rho_X: \Sigma(X \times BX) \longrightarrow B\Sigma^*X \quad (X \in \mathcal{C})$$

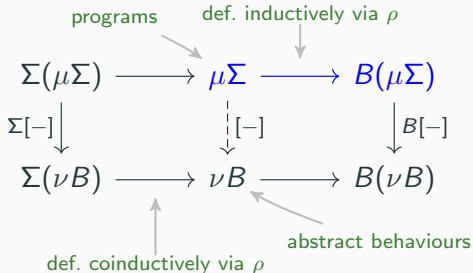
Operational model, denotational model, semantics for free!



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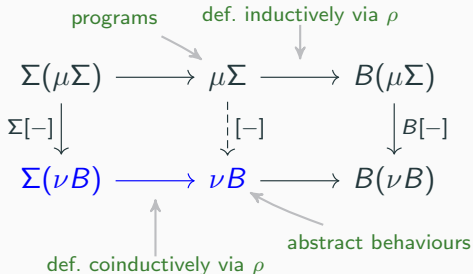
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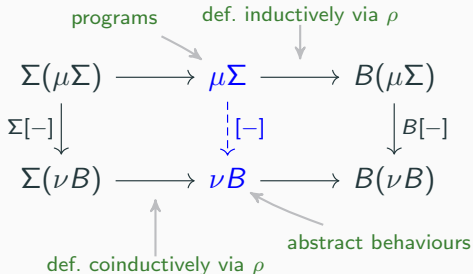
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Operational model, denotational model, **semantics** for free!



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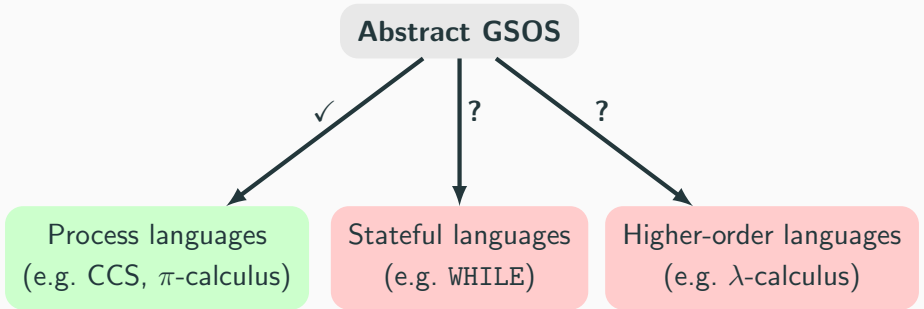
Operational model, denotational model, semantics for free!

$$\begin{array}{ccccc} & \text{programs} & & \text{def. inductively via } \rho & \\ & \searrow & & \downarrow & \\ \Sigma(\mu\Sigma) & \longrightarrow & \mu\Sigma & \longrightarrow & B(\mu\Sigma) \\ \Sigma[-] \downarrow & & \vdots[-] & & \downarrow B[-] \\ \Sigma(\nu B) & \longrightarrow & \nu B & \longrightarrow & B(\nu B) \\ & & \text{def. coinductively via } \rho & \nearrow & \text{abstract behaviours} \end{array}$$

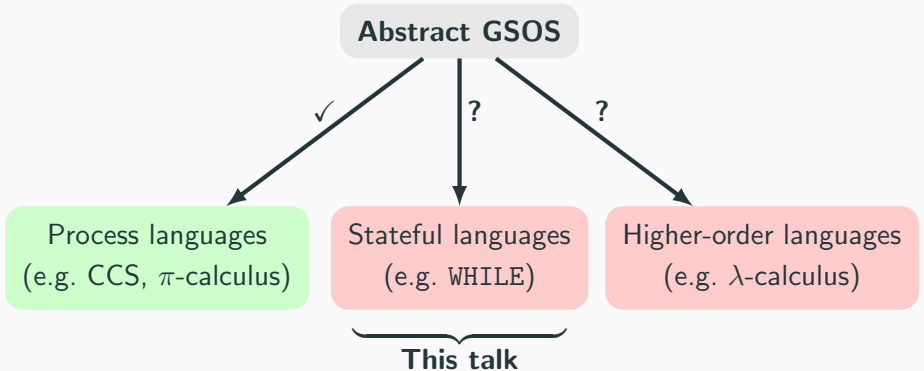
**Compositionality for free:**  $[-]$  is a  $\Sigma$ -algebra morphism!



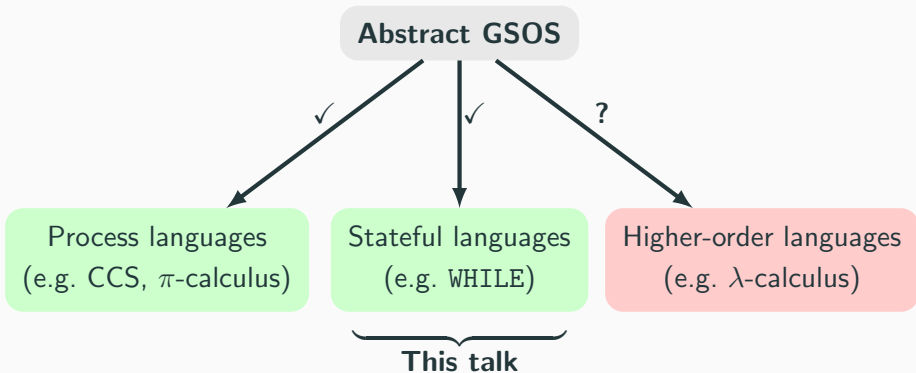
# Abstract GSOS: Applications



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# Abstract GSOS: Applications



# WHILE Language: SOS Specification

$$\text{skip} \frac{}{s, \text{skip} \downarrow s}$$

$$\text{asn} \frac{}{s, (x := e) \downarrow s[x \leftarrow [e]_s]}$$

$$\text{while1} \frac{}{s, \text{while } e \text{ } p \downarrow s} [e]_s = 0$$

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$$\text{seq1} \frac{s, p \downarrow s'}{s, (p; q) \rightarrow s', q}$$

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with finite support  
 $\{x \in \text{Vars} : s(x) \neq 0\}$

$$s, s' \in \text{States} \quad (= \text{Vars} \rightarrow \mathbb{N})$$

# Stateful SOS

$\Sigma$  (signature),  $S$  (set of states)

A **stateful SOS specification** is a set of rules of the form

$$\frac{\{s, p_i \rightarrow s_i, q_i\}_{i \in W} \quad \{s, p_i \downarrow s_i\}_{i \notin W}}{s, f(p_1, \dots, p_n) \rightarrow s', t(\dots, p_i, q_i, \dots) \text{ or } \downarrow s'}$$

(exactly one rule for each  $f \in \Sigma$ , states  $s, s_1, \dots, s_n$  and  $W \subseteq \{1, \dots, n\}$ ).

Categorically: **stateful SOS laws**

$$\lambda_X : \underbrace{S \times \Sigma(X \times S \times (X + 1))}_{\text{premises}} \longrightarrow \underbrace{S \times (\Sigma^* X + 1)}_{\text{conclusion}} \quad (X \in \text{Set}).$$

# WHILE Language: SOS Specification

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**Stateful SOS specification (up to completing premisses)**

# From Stateful SOS to Abstract GSOS

$$\lambda_X : S \times \Sigma(X \times S \times (X + 1)) \rightarrow S \times (\Sigma^* X + 1)$$

induces abstract GSOS law

$$\rho_X : \Sigma(X \times BX) \rightarrow B\Sigma^* X \quad \text{where} \quad BX = (S \times (X + 1))^S$$

Operational model  $(\mu\Sigma)$ , denotational model  $(\nu B)$ , compositionality

$$\begin{array}{ccccc} \Sigma(\mu\Sigma) & \longrightarrow & \mu\Sigma & \longrightarrow & B(\mu\Sigma) \\ \Sigma[-] \downarrow & & \downarrow [-] & & \downarrow B[-] \\ \Sigma(\nu B) & \longrightarrow & \nu B & \longrightarrow & B(\nu B) \end{array}$$

## Resumption Semantics

$$\begin{array}{ccccc} \Sigma(\mu\Sigma) & \longrightarrow & \mu\Sigma & \longrightarrow & B(\mu\Sigma) \\ \Sigma[-] \downarrow & & \downarrow [-] & & \downarrow B[-] \\ \Sigma(\nu B) & \longrightarrow & \nu B & \longrightarrow & B(\nu B) \end{array}$$

For  $BX = (S \times (X + 1))^S$ :

$\nu B = |S|$ -branching  $S$ -labelled possibly infinite trees.

This yields a **resumption semantics**: programs run in an environment that can observe and modify intermediate states.

### Example (WHILE)

$$[x := 1; x := x + 1] \neq [x := 1; x := x * 2]$$



## Resumption Semantics

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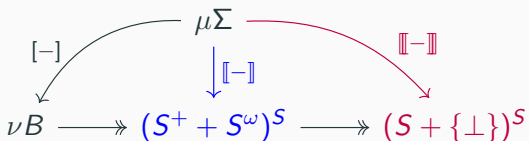
### Example (WHILE)

$$[x := 1; x := x + 1] \neq [x := 1; x := x * 2]$$

**Usually too fine-grained!** Coarser semantic domains?

# Semantic Domains for Stateful SOS

Every stateful SOS specification yields three semantics (def. coinductively):



**Resumption semantics:** Env. can observe/modify intermediate states.

**Trace semantics:** Env. can observe intermediate states.

**Termination semantics:** Env. can only observe the final state (if any).

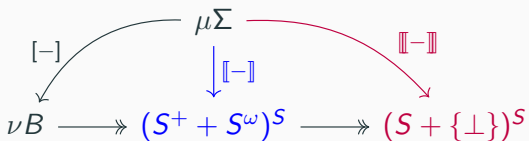
## Example (WHILE)

$$\llbracket x := 1; x := x + 1 \rrbracket = \llbracket x := 1; x := x * 2 \rrbracket$$

$$\llbracket x := 1; x := 2 \rrbracket \neq \llbracket x := 2; x := 2 \rrbracket$$

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## Semantic Domains for Stateful SOS



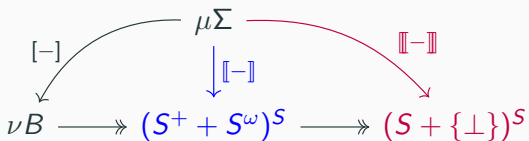
Are these three semantics compositional?

$$[p_i] = [q_i] \quad (i = 1, \dots, n) \quad \stackrel{?}{\implies} \quad [f(p_1, \dots, p_n)] = [f(q_1, \dots, q_n)]$$

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## Semantic Domains for Stateful SOS



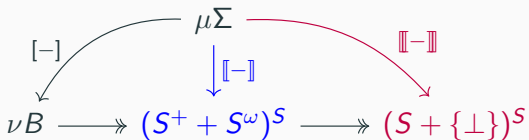
Are these three semantics compositional?

$$[p_i] = [q_i] \quad (i = 1, \dots, n) \quad \xrightarrow[\text{TP'97}]{\checkmark} \quad [f(p_1, \dots, p_n)] = [f(q_1, \dots, q_n)]$$

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# Compositionality



## Example (Compositionality fails for $[-]$ and $[[ - ]]$ )

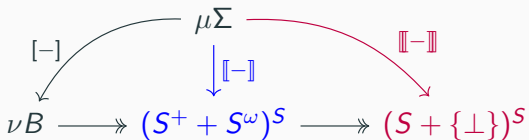
Extend WHILE by adding a unary operator  $u(\cdot)$  with

$$\frac{s, p \rightarrow s', p'}{s, u(p) \rightarrow 0, u(p')} \quad \frac{s, p \downarrow s'}{s, u(p) \downarrow s'}$$

For  $t_1 = (x := 1; x := x + 1)$  and  $t_2 = (x := 1; x := x * 2)$  we have

$$\begin{array}{ll} \llbracket t_1 \rrbracket = \llbracket t_2 \rrbracket & \text{but} \quad \llbracket u(t_1) \rrbracket \neq \llbracket u(t_2) \rrbracket, \\ \llbracket t_1 \rrbracket = \llbracket t_2 \rrbracket & \text{but} \quad \llbracket \llbracket u(t_1) \rrbracket \rrbracket \neq \llbracket \llbracket u(t_2) \rrbracket \rrbracket. \end{array}$$

# Compositionality



## Theorem

Compositionality is undecidable for  $\llbracket\text{-}\rrbracket$  and  $\llbracket\text{-}\rrbracket$ .

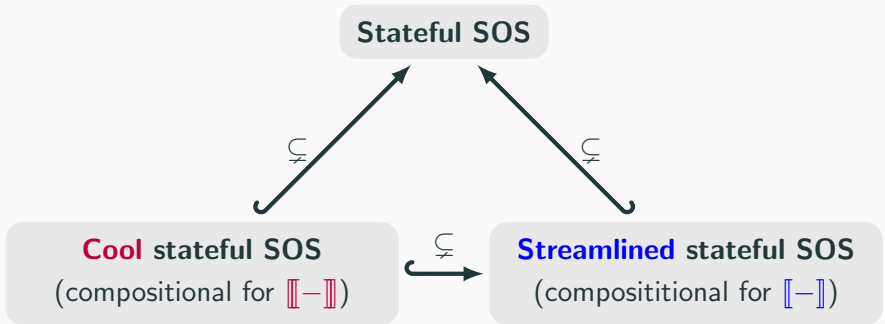
**Proof (reduction from halting problem):** Form stateful SOS spec.



Then TM halts  $\iff \mathcal{S}$  non-compositional. □

# Streamlining and Cooling Stateful SOS

We devise two restrictions of stateful SOS that guarantee compositionality:



cf. van Glabbeek 2005, Abou-Saleh & Pattinson 2011

# Streamlined Stateful SOS



# Streamlined Stateful SOS

## Stateful SOS

$$\frac{\{s, p_i \rightarrow s_i, q_i\}_{i \in W} \quad \{s, p_i \downarrow s_i\}_{i \notin W}}{s, f(p_1, \dots, p_n) \rightarrow s', t(\dots, p_i, q_i, \dots) \text{ or } \downarrow s'}$$

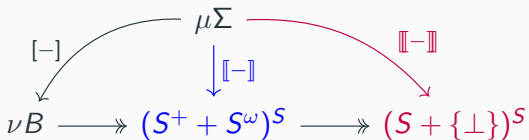
**Passive operator**  $f \in \Sigma$ : given by rule of the form

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**Streamlined spec.:** For active  $f$ , rules have the following forms ( $j$  fixed):

$$\frac{\dots \quad s, p_j \rightarrow s_j, q_j \quad \dots}{s, f(p_1, \dots, p_j, \dots, p_n) \rightarrow s_j, f(p_1, \dots, q_j, \dots, p_n) \text{ or } s_j, q_j}$$
$$\frac{\{s, p_i \rightarrow s_i, q_i\}_{i \in W} \quad \{s, p_i \downarrow s_i\}_{i \notin W}}{s, f(p_1, \dots, p_j, \dots, p_n) \rightarrow s', t(p_1, \dots, p_j, \dots, p_n) \text{ or } \downarrow s'}$$

# Compositionality



## Example (Compositionality fails for $\llbracket - \rrbracket$ )

Extend WHILE by adding a unary operator  $u(\cdot)$  with

$$\frac{s, p \rightarrow s', p'}{s, u(p) \rightarrow 0, u(p')} \quad \frac{s, p \downarrow s'}{s, u(p) \downarrow s'}$$

**Not streamlined!**

For  $t_1 = (x := 1; x := x + 1)$  and  $t_2 = (x := 1; x := x * 2)$  we have

$$\llbracket t_1 \rrbracket = \llbracket t_2 \rrbracket \quad \text{but} \quad \llbracket u(t_1) \rrbracket \neq \llbracket u(t_2) \rrbracket.$$

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**Streamlined!**

# Streamlined Stateful SOS

## Theorem (Compositionality of trace semantics)

For every streamlined stateful SOS specification,

$$\llbracket p_i \rrbracket = \llbracket q_i \rrbracket \quad (i = 1, \dots, n) \quad \Longrightarrow \quad \llbracket f(p_1, \dots, p_n) \rrbracket = \llbracket f(q_1, \dots, q_n) \rrbracket$$

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## Example

WHILE is streamlined, thus compositional w.r.t. trace semantics.

## Example (Interrupt handling)

Extend WHILE with an interrupt flag  $i$  and modify rules to

$$\frac{s, p \rightarrow s', p'}{s, (p; q) \rightarrow s', (p'; q)} [i]_s = 0 \quad \frac{s, p \rightarrow s', p'}{s, (p; q) \rightarrow s', q} [i]_s \neq 0$$

Still streamlined, thus compositional w.r.t. trace semantics!

# Cool Stateful SOS

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## Stateful SOS

$$\frac{\{s, p_i \rightarrow s_i, q_i\}_{i \in W} \quad \{s, p_i \downarrow s_i\}_{i \notin W}}{s, f(p_1, \dots, p_n) \rightarrow s', t(\dots, p_i, q_i, \dots) \text{ or } \downarrow s'}$$

**Passive operator**  $f \in \Sigma$ : given by rule of the form

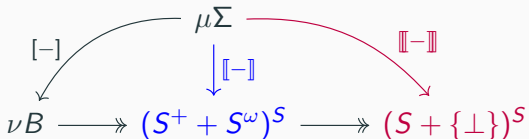
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**Cool spec.:** For active  $f$ , rules have the following forms (for fixed  $j$ ):

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$$\frac{s, p_j \downarrow s'}{s, f(p_1, \dots, p_j, \dots, p_n) \rightarrow \underbrace{s''}_{\text{depend on } s' \text{ but not } s}, t(p_1, \dots, p_j, \dots, p_n) \text{ or } \downarrow s''}$$

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Extend WHILE by adding a unary operator  $u(\cdot)$  with

**Uncool!**

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Cool!

# Cool Stateful SOS

## Theorem (Compositionality of termination semantics)

For every cool stateful SOS specification,

$$\llbracket p_i \rrbracket = \llbracket q_i \rrbracket \quad (i = 1, \dots, n) \quad \Longrightarrow \quad \llbracket f(p_1, \dots, p_n) \rrbracket = \llbracket f(q_1, \dots, q_n) \rrbracket$$

# Cool Stateful SOS

## Theorem (Compositionality of termination semantics)

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## Example

WHILE is cool, thus compositional w.r.t. termination semantics.

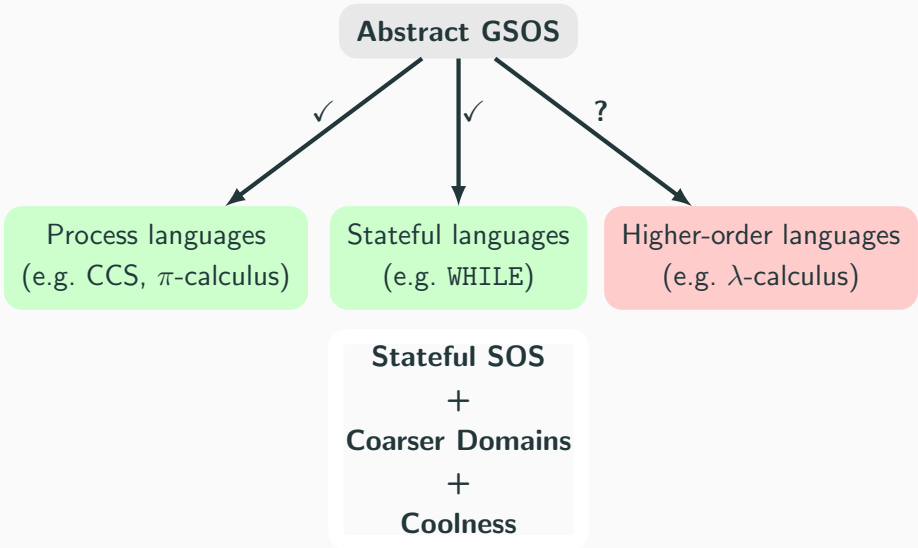
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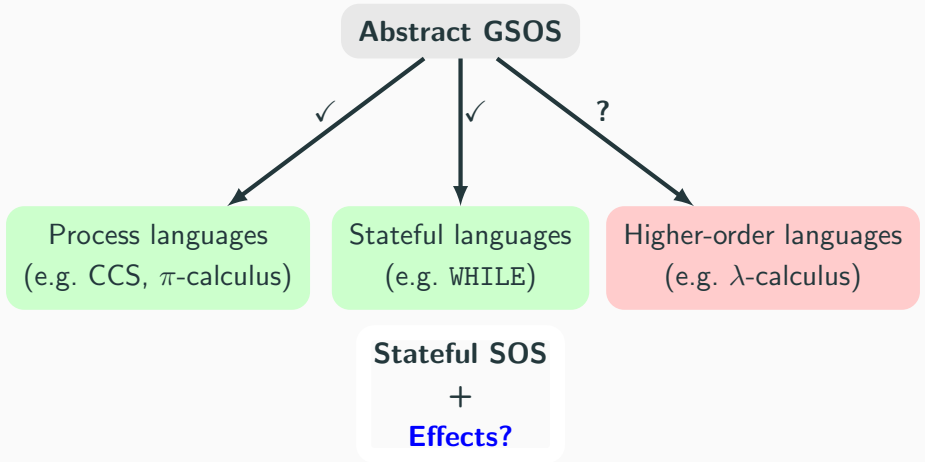
$$\frac{s, p \rightarrow s', p'}{s, (p; q) \rightarrow s', (p'; q)} [i]_s = 0 \quad \frac{s, p \rightarrow s', p'}{s, (p; q) \rightarrow s', q} [i]_s \neq 0$$

**Uncool!** (but compositional for trace semantics)

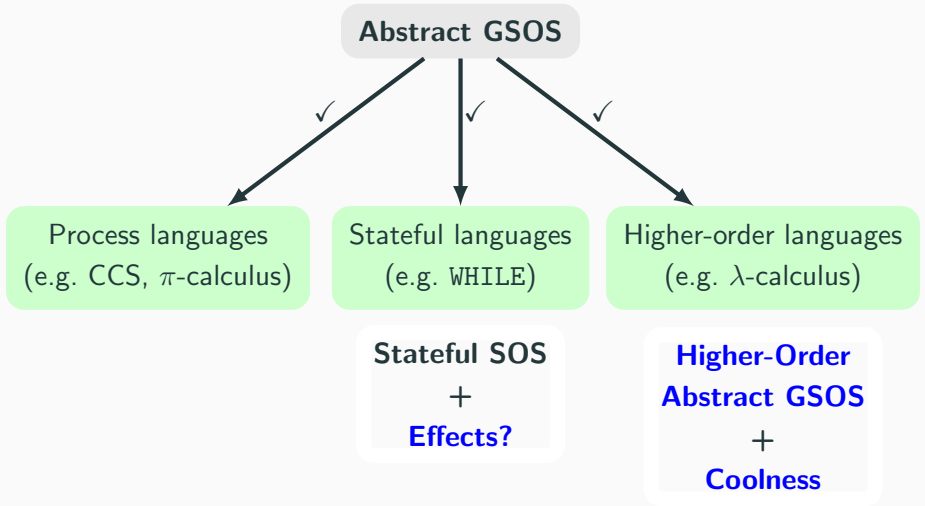
# Conclusion and Future Work



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# Appendix

# Cool Stateful SOS: Towards a Categorical View

## Stateful SOS

$$\frac{\{s, p_i \rightarrow s_i, q_i\}_{i \in W} \quad \{s, p_i \downarrow s_i\}_{i \notin W}}{s, f(p_1, \dots, p_n) \rightarrow s', t(\dots, p_i, q_i, \dots) \text{ or } \downarrow s'}$$

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Thus, rules for  $f$  determined by a natural transformation

$$\pi_X^f: S \times X^n \rightarrow S \times (\Sigma^* X + 1) \quad (X \in \text{Set}).$$



## Cool Stateful SOS: Towards a Categorical View

**Cool spec.:** For active  $f$ , rules have the following forms (for fixed  $j$ ):

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Thus, rules for active  $f$  determined by a natural transformation

$$\alpha_X^f: S \times X^{j-1} \times 1 \times X^{n-j} \rightarrow S \times (\Sigma^* X + 1) \quad (X \in \text{Set}).$$

Natural transformations  $\alpha_X^f$  and  $\pi_X^f$  (for  $f$  passive) yield stateful SOS law

$$\lambda_X: S \times \Sigma(X \times S \times (X + 1)) \rightarrow S \times (\Sigma^* X + 1) \quad (X \in \text{Set}).$$

**Categorical proof/generalization of compositionality results?**